Log:

adding navigator to odometer constructor (and getNav method to odo)

adding odometer to navigator constructor

getting rid of creating navigator in execution.java because of odometer constructor\

adding setRotationSpeed / setSpeed method to Navigator

changing odometer calculation (x axis is still 0 degree)

changing how navigator get radius and wheel distance (now they get them from odometer)

adding turn method in navigator (it turns to relative angle to the robot

Friday:

getting rid of circle method in odometer

odometer constructor theta = 0

change getPosition (first one) method because theta is in degree now

if using eric method, change getTheta and getPosition (theta)

in navigator, change turnTo method’s getTheta to \*180/PI

adding getLocation method and at the end of doLocalization

changing navigator sleep to public